

Automata

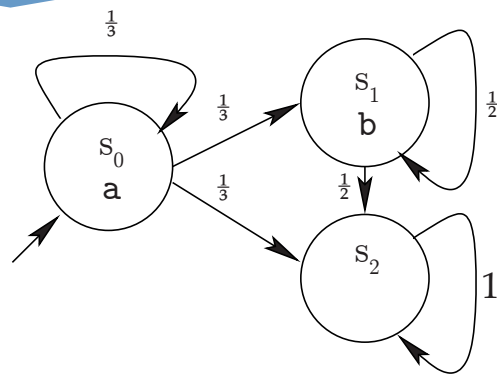
Approach to Probabilistic Verification

- p-automata read an entire Markov chain as input and either accept or reject it.
- Their definition combines the combinatorial structure of alternating automata with the ability to quantify probabilities of regular sets of paths.
- Two probabilistic quantifiers: one tallies probabilities of immediate next locations (reminiscent of the X operator in PCTL); the other measures the probabilities of regular path sets.

- Transitions are positive Boolean formulas with an extended base set, combining states q with threshold obligations: $\llbracket q \rrbracket_{\geq 0.5}$ says that the path set represented by q has probability ≥ 0.5 .
- A probabilistic separation operator $*$ decomposes the witness path set for a probability threshold into disjoint subsets: $*(\llbracket q_1 \rrbracket_{\geq p_1}, \llbracket q_2 \rrbracket_{\geq p_2})$ says that the path set determined by state q_1 has probability at least p_1 for $i=1,2$; and that the sets measured by these probabilities are disjoint. (Think "disjoint and".)

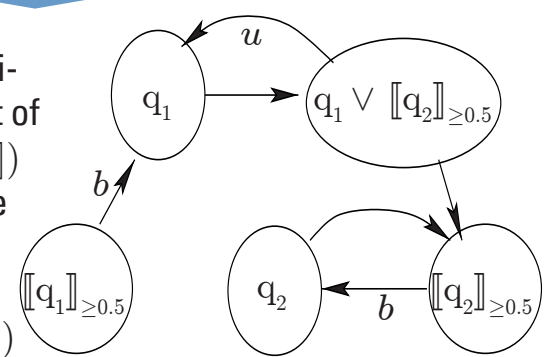
Markov Chains

A finitely branching, countable labeled Markov chain M over set of propositions \mathbb{A} is a tuple $\langle S, P, s^{\text{in}}, L \rangle$, where S is a countable set of locations, P a stochastic matrix, s^{in} initial location, and $L(s)$ the set of propositions true in location s .



p-Automata

A p-automaton \mathcal{A} is a tuple $\langle \Sigma, Q, \delta, \phi^{\text{in}}, \alpha \rangle$, where Σ is a finite input alphabet, Q is a set of states, $\delta: Q \times \Sigma \rightarrow \mathcal{B}^+(Q \cup \llbracket Q \rrbracket)$ the transition function, ϕ^{in} the initial condition, $\alpha \subseteq Q$ an acceptance condition, and $\llbracket Q \rrbracket = \{ \llbracket q_i \rrbracket_{\geq p_i}, *(\llbracket q_1 \rrbracket_{\geq p_1}, \dots, \llbracket q_n \rrbracket_{\geq p_n}) \mid q_i \in Q, p_i \in [1, 0], n \in \mathbb{N} \}$.



Example

Let $\mathcal{A} = \langle \mathcal{P}(\{a, b\}), \{q_1, q_2\}, \delta, \llbracket q_1 \rrbracket_{\geq 0.5}, \{q_2\} \rangle$ be a p-automaton with δ as follows (and as in the graph above):

$$\delta(q_1, \{a, b\}) = \delta(q_1, \{a\}) = q_1 \vee \llbracket q_2 \rrbracket_{\geq 0.5}$$

$$\delta(q_2, \{a, b\}) = \delta(q_2, \{b\}) = \llbracket q_2 \rrbracket_{\geq 0.5}$$

$$\delta(q_1, \{\}) = \delta(q_1, \{b\}) = \delta(q_2, \{a\}) = \delta(q_2, \{\}) = \text{false}$$

Term $\llbracket q_2 \rrbracket_{\geq 0.5}$ represents the recursive property ϕ , that atomic

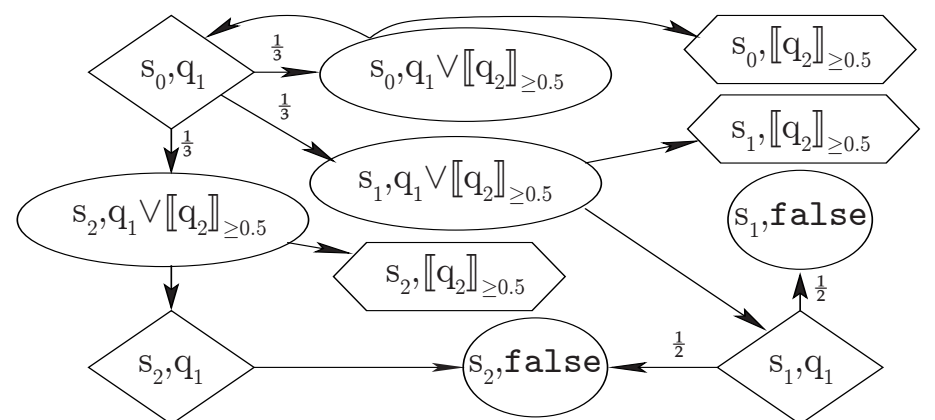
proposition b holds at the location presently read by q_2 and that ϕ will hold with probability at least 0.5 in the next locations. State q_1 asserts that it is possible to get to a location that satisfies $\llbracket q_2 \rrbracket_{\geq 0.5}$ along a path that satisfies atomic proposition a . The initial condition $\llbracket q_1 \rrbracket_{\geq 0.5}$ means the set of paths satisfying $aU\phi$ has probability at least 0.5.

Games for acceptance & simulation

Acceptance $M \in \mathcal{L}(\mathcal{A})$ and simulation $\mathcal{A} \leq \mathcal{B}$ can be decided through a series of stochastic games and games. (EXPTIME in the sizes of \mathcal{A} and M . Some conditions on \mathcal{A} and \mathcal{B} for simulation.)

Example The stochastic game $G_{M, (\{q_1\})}$ for the SCC $(\{q_1\})$ depicts stochastic configurations as diamond and configurations from other SCCs as hexagons (with the hexagon labeled $(s_1, \llbracket q_2 \rrbracket_{\geq 0.5})$ having value 1 and all others having value 0). As none of the configurations are accepting, P_0 can only win by reaching optimal hexagons. Hexagon $(s_1, \llbracket q_2 \rrbracket_{\geq 0.5})$ has value 1 and is the optimal choice for P_0 from configuration $(s_1, q_1 \vee \llbracket q_2 \rrbracket_{\geq 0.5})$. As $(s_2, q_1 \vee \llbracket q_2 \rrbracket_{\geq 0.5})$ has value 0, the value for P_0 of diamond configuration (s_1, q_1) is 0.5. Initial configuration $(s_0, \llbracket q_1 \rrbracket_{\geq 0.5})$ is a trivial

bounded SCC; its value equals 1 as $\frac{1}{3} \text{val}(s_0, q_1 \vee \llbracket q_2 \rrbracket_{\geq 0.5}) + \frac{1}{3} \text{val}(s_1, q_1 \vee \llbracket q_2 \rrbracket_{\geq 0.5}) + \frac{1}{3} \text{val}(s_2, q_1 \vee \llbracket q_2 \rrbracket_{\geq 0.5})$ is 0.5. Thus $M \in \mathcal{L}(\mathcal{A})$.



Properties

- p-automata are closed under Boolean operations.
- The language of a p-automaton is closed under bisimulation.
- Markov chain M can be embedded as a p-automaton accepting the language of Markov chains that are bisimilar to M .
- PCTL formula ϕ can be expressed as language $\mathcal{L}(\mathcal{A})$, and PCTL model checking can be reduced to deciding the accept-

ance of Markov chains by p-automata \mathcal{A} . The complexity of the acceptance game then matches that of model checking.

- Language containment and emptiness are equi-solvable.
- Simulation between p-automata that stem from Markov chains or PCTL formulas is decidable in EXPTIME and under-approximates language containment.

Conclusions

- p-automata are a complete abstraction framework for PCTL: if an infinite Markov chain M satisfies a PCTL formula ϕ , there is a finite p-automaton that abstracts M and whose language is contained in that of the p-automaton for ϕ .
- Emptiness, universality, and containment of p-automata seem

tightly related to the open problem of decidability of PCTL satisfiability.

Full paper p-Automata: New Foundations for Discrete-Time Probabilistic Verification. To appear in Proc. of QEST 2010.